

MODEL 163 with CODE (414a) Electric glass sliding/pop-up roof

Position measurement for the **sliding/pop-up roof (M12)** is accomplished by means of a position sensor integrated into the evaluation electronic module. One rectangular position sensor is integrated into the evaluation electronic module. This means that when the pop-up roof is completely opened the counter should read "0". The "0" position can be set with the **synchronization** function.



In the synchronized state the evaluation electronic module for the **sliding /pop-up roof (M12)** continuously compares the current value of the position counter with the stored end positions while the roof is moving. If one of these end positions is reached, it switches off the motor (pre-lock-up switch-off).

	Sliding/pop-up roof, location/purpose/design/function		GF77.20-P-4100GH
	Synchronizing sliding /pop-up roof, function		GF77.20-P-3002GH